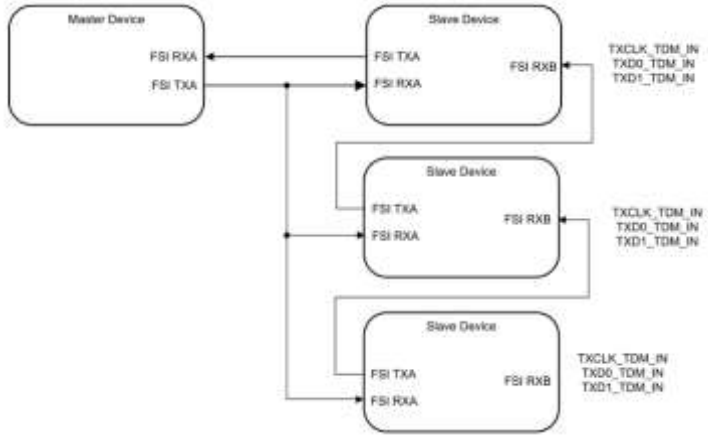
F28P55x编程实例Labs-FSI

- Code Composer Studio
- C2000Ware
- LaunchXL-F28P55x

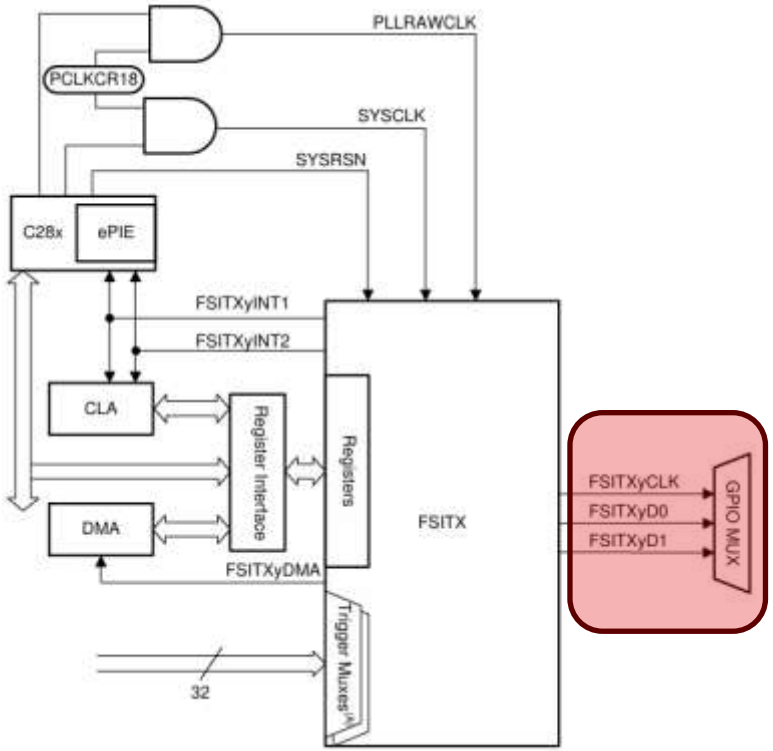
FSI

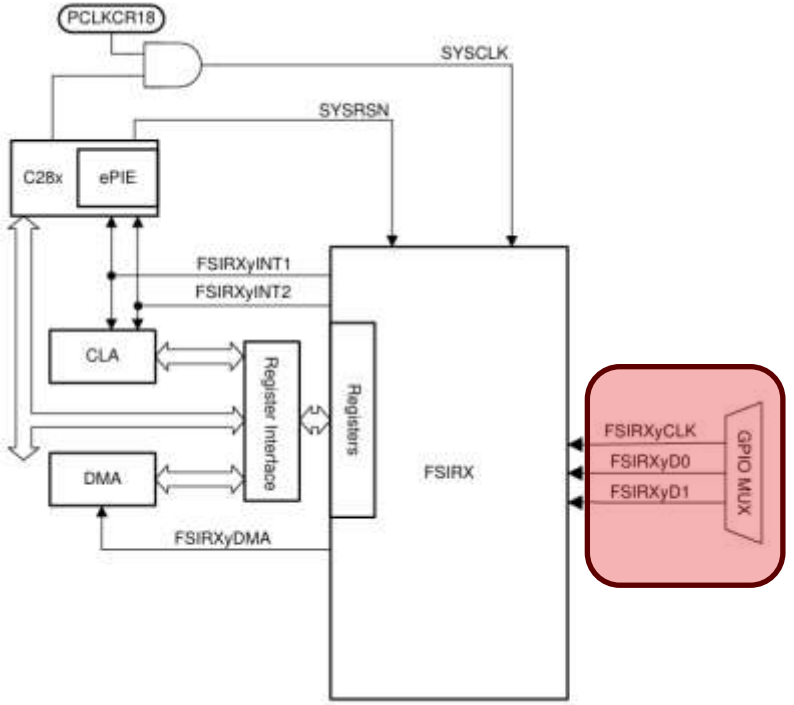
Fast Serial Interface

- **通信速率最高200Mbps**
- **支持菊花链/星型多机**连接拓扑
- **具有独立接收端/发送端**



类星型多机通信拓扑





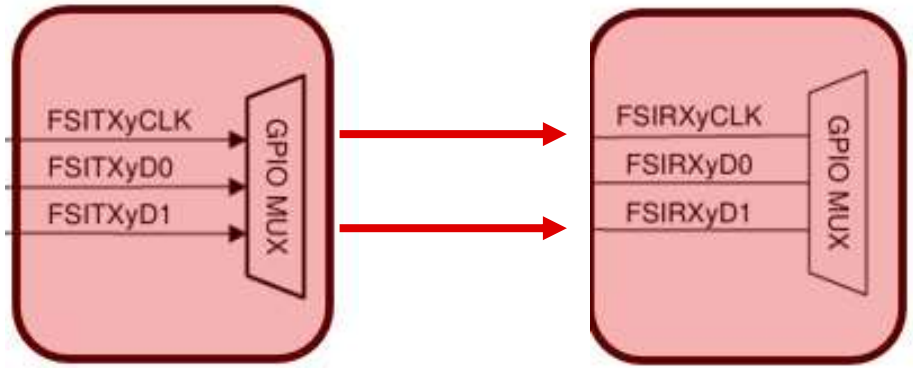
FSI

功能实现

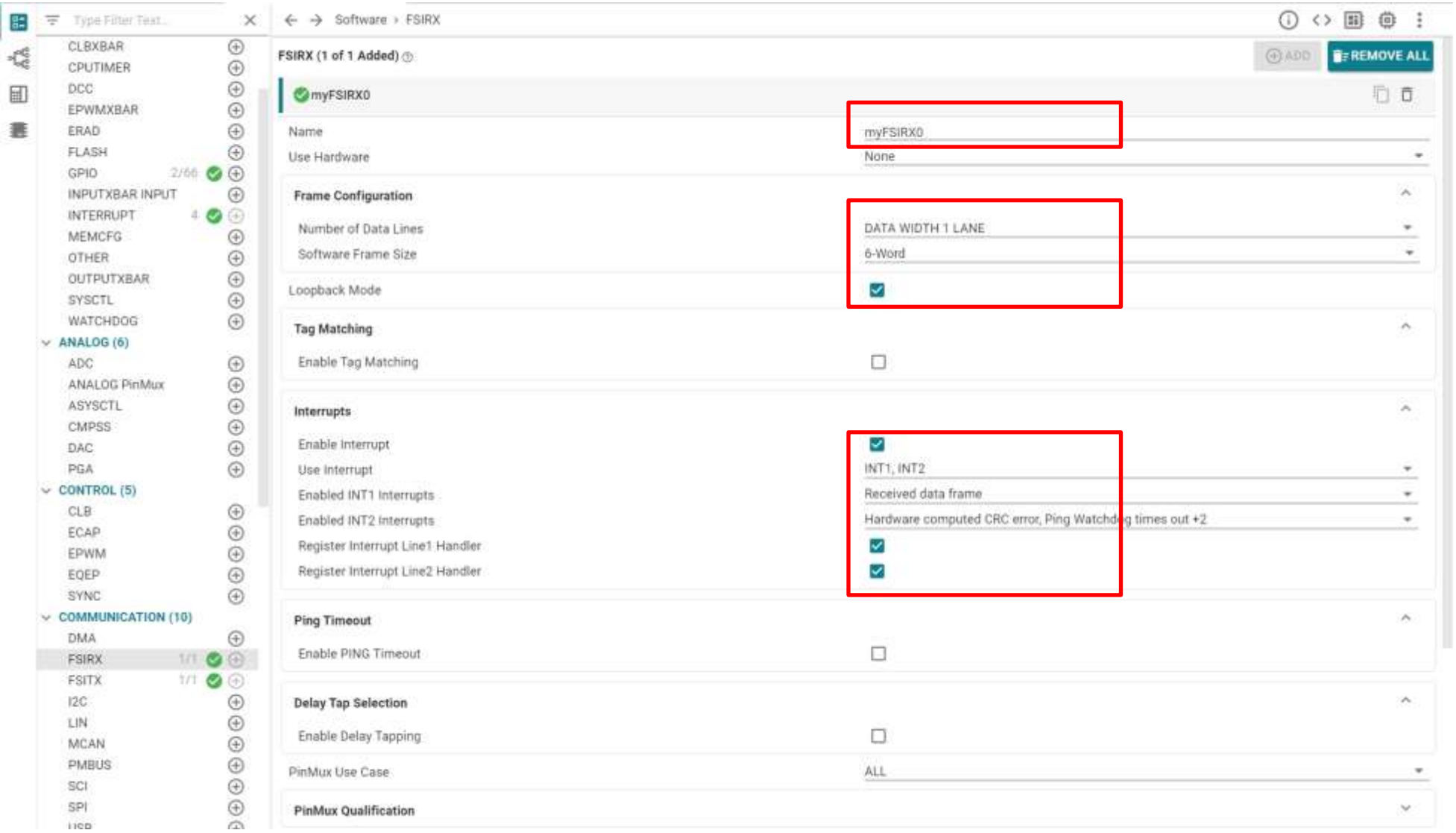
用Sysconfig配置FSI，实现接收模块FSIRX和发送模块FSITX之间的回环(loop-back)数据通信

实现步骤

- 复制空白工程
- Sysconfig配置FSIRX
- Sysconfig配置FSITX
- Sysconfig配置GPIO驱动LED4/LED5
- 编写应用代码

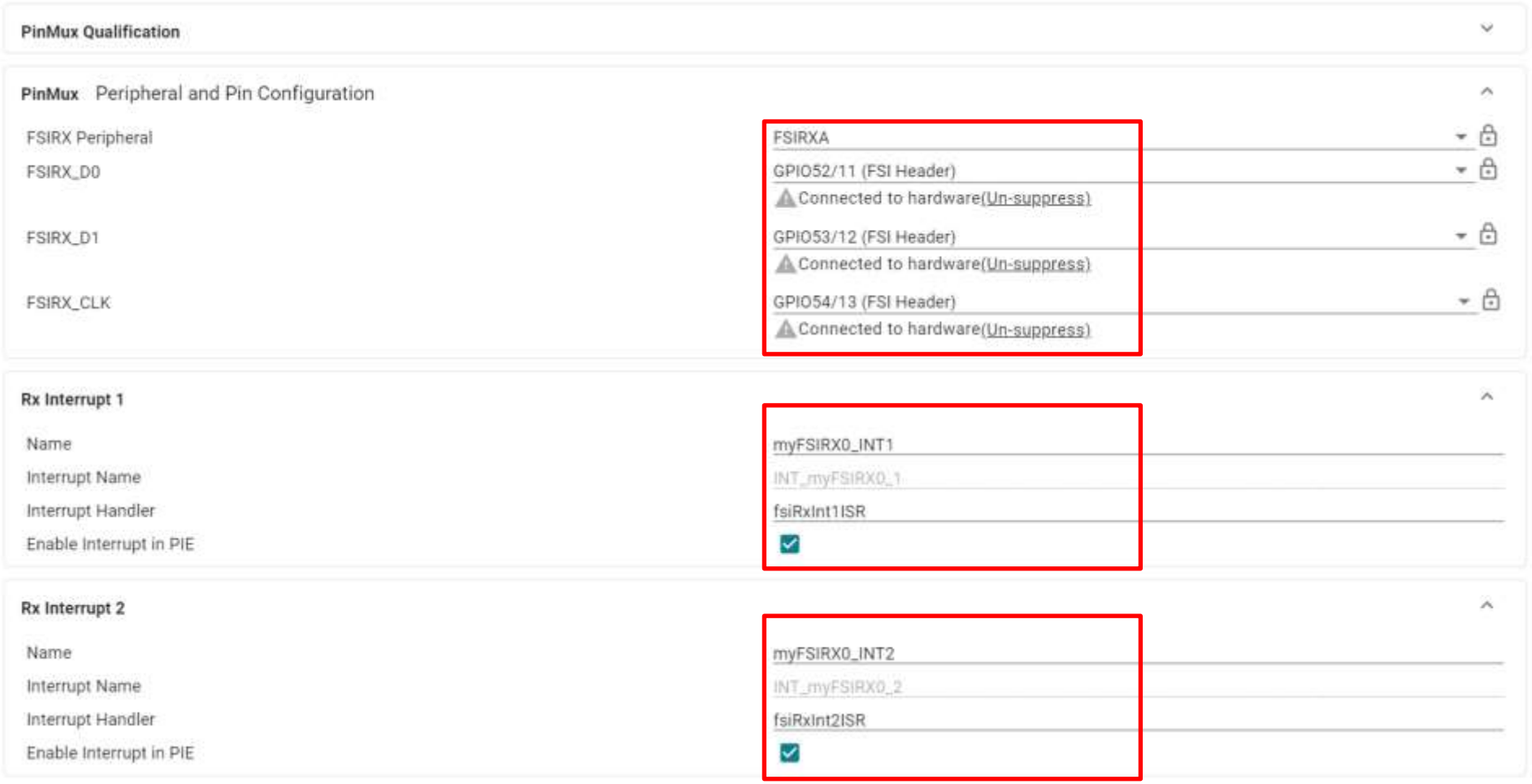


配置FSIRX



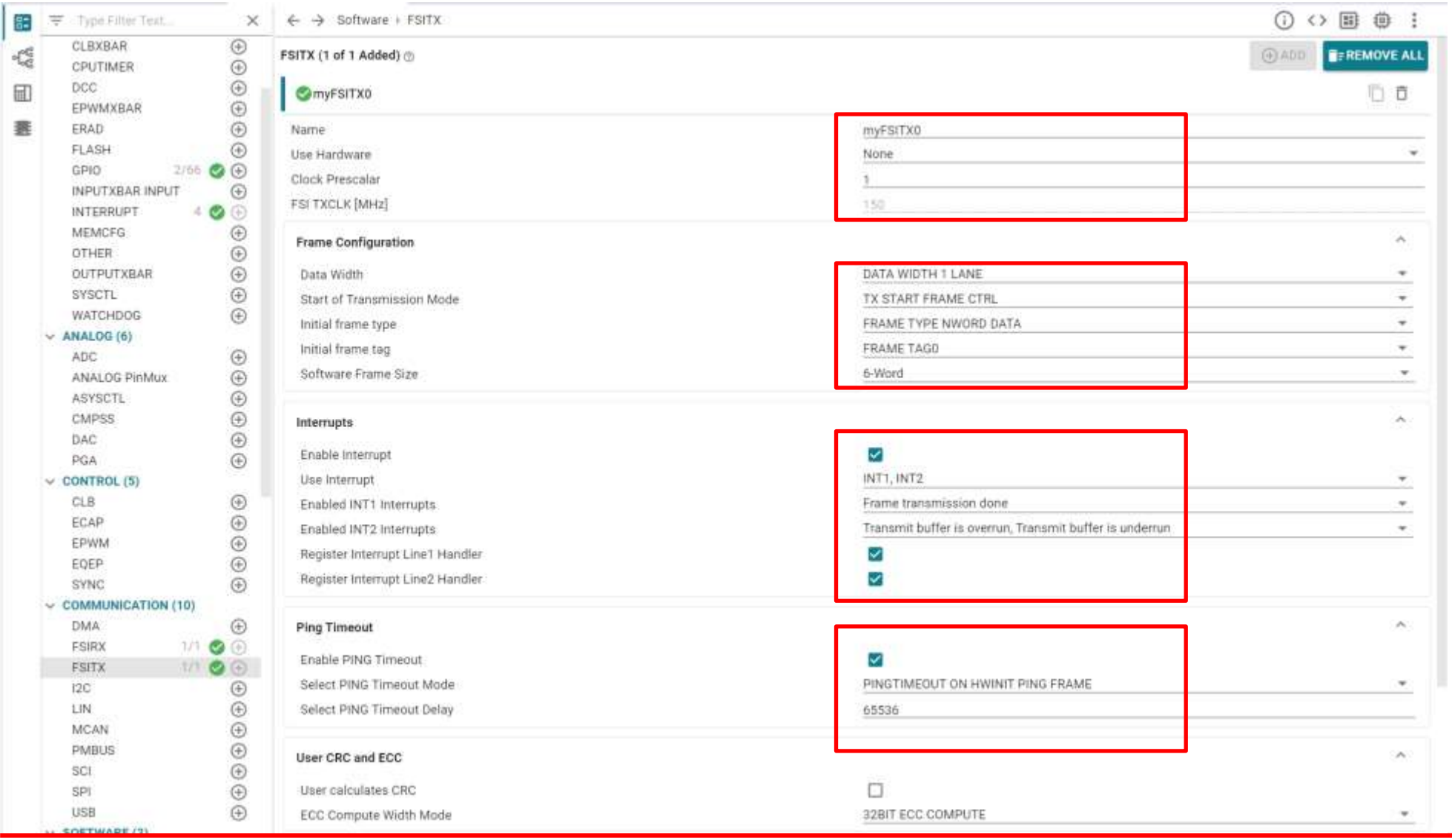
- 单线传输
- 6字长度
- 使能回环模式
- 使能中断

配置FSIRX



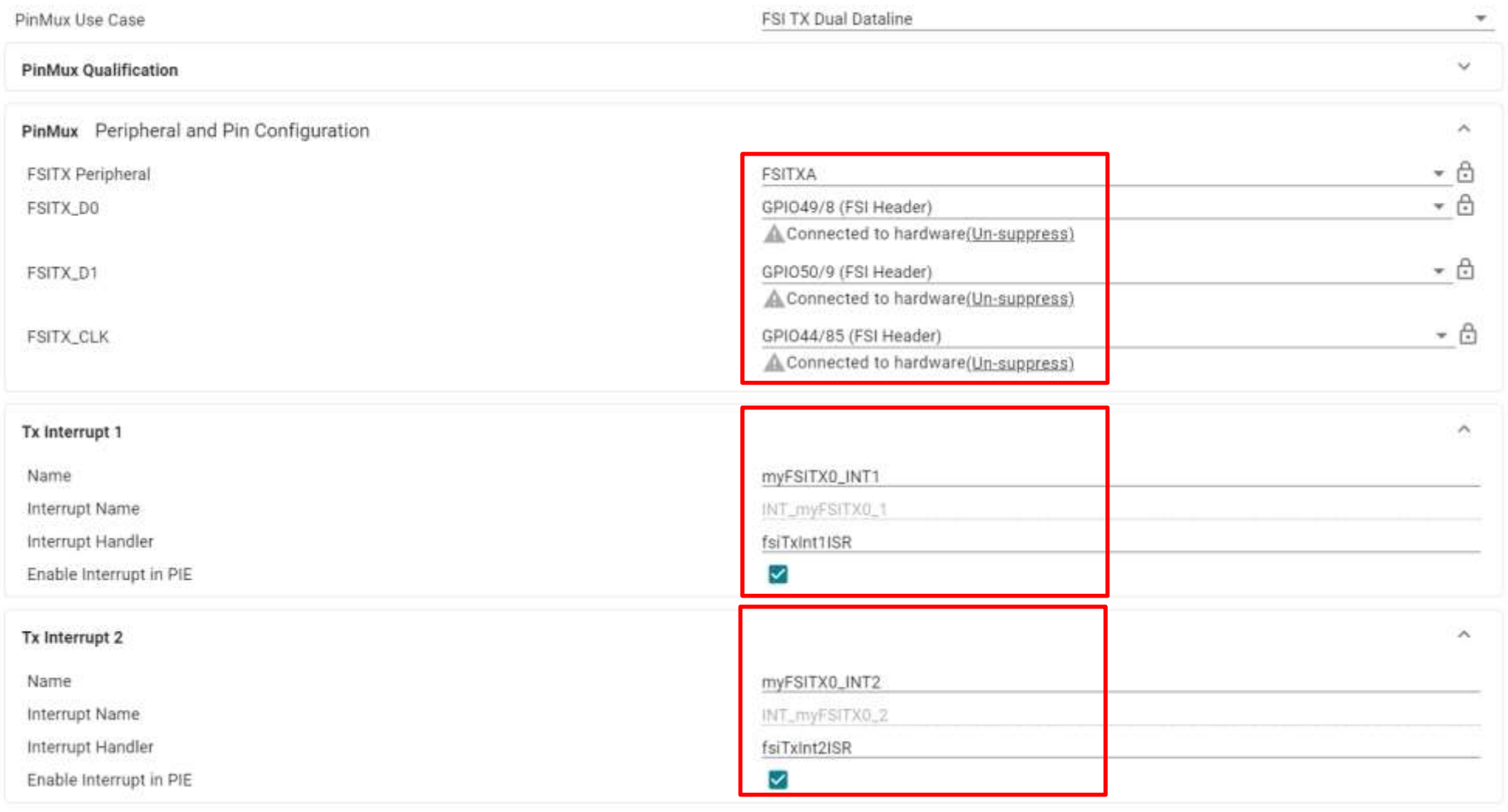
- INT1接收中断
- INT2 超时、CRC

配置FSITX



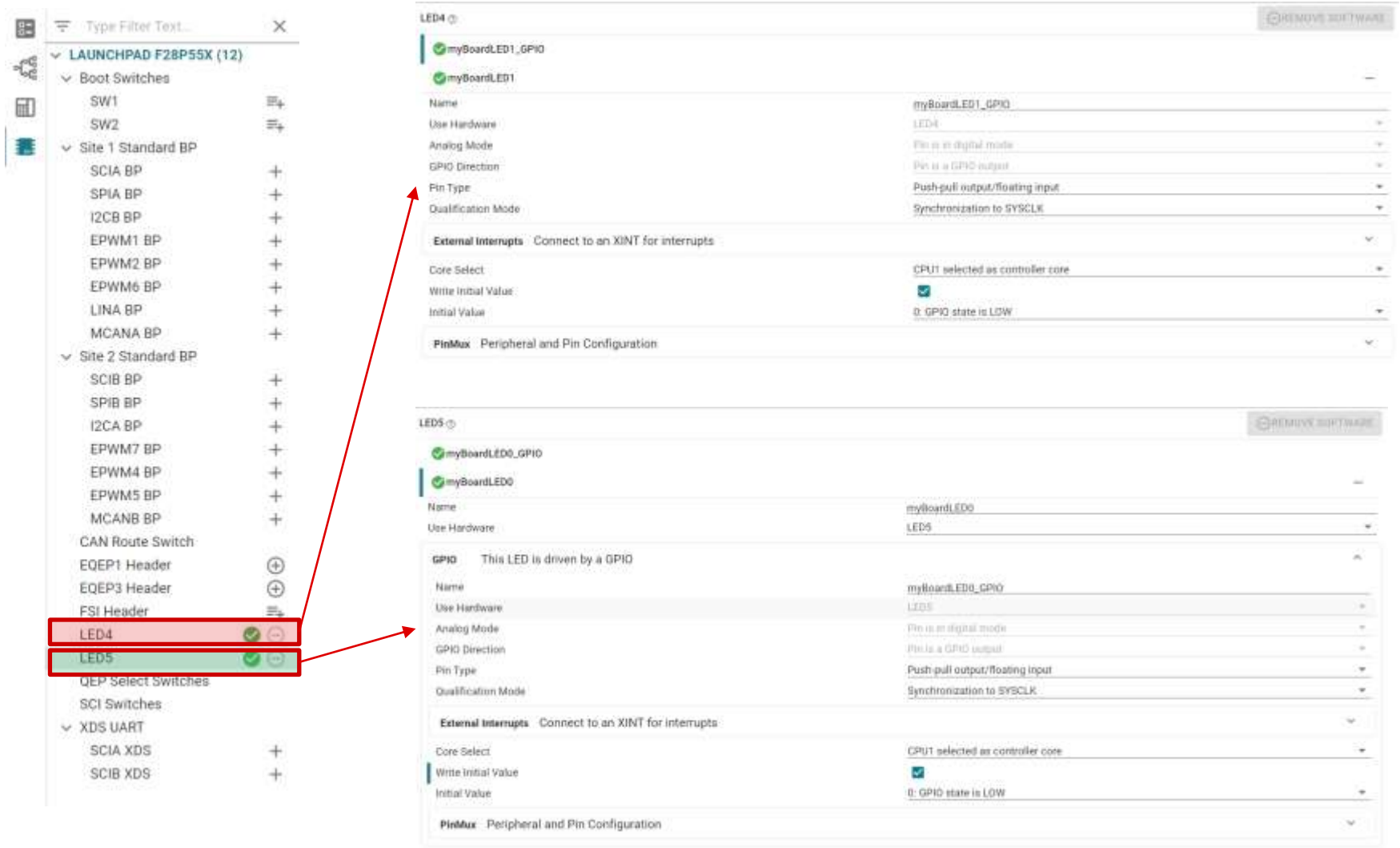
- 单线传输
- 6字长度
- 使能中断
- 使能Ping超时

配置FSITX



- INT1 发送中断
- INT2 Ping超时中断

配置LED



- LED4-发送数据闪烁
- LED5-接收数据闪烁

应用代码

```
//
// Included Files
//
#include "driverlib.h"
#include "device.h"
#include "board.h"
```

```
//
//Globals
//
uint16_t txBufData[16];                    //used to write to FSI transmit buffer
uint16_t rxDataArray[16];                  //buffer used to access FSI receive buffer
uint32_t dataFrameCntr = 0;                //counts how many data frames have been received
uint16_t txEventSts = 0, rxEventSts = 0;   //captures FSITX/FSIRX event status in case of error
uint16_t txIntReceived = 0;                //flag to signal TX interrupt has occurred
uint16_t rxIntReceived = 0;                //flag to signal RX interrupt has occurred
uint32_t softwareTimeoutCntr = 0x100000;   //software watchdog counter in case interrupts fail

uint16_t txcnt = 0;
uint16_t rxcnt = 0;
```

应用代码

```
__interrupt void fsiRxInt1ISR(void)
{
    //
    //Set flag that interrupt has occurred, capture FSIRX event status, increment data frame count.
    //
    rxIntReceived = 1;
    rxEventSts = FSI_getRxEventStatus(FSIRXA_BASE);
    dataFrameCntr++;

    //
    //Transfer data from receive buffer to array
    //
    FSI_readRxBuffer(FSIRXA_BASE, rxDataArray, myFSIRX0_nWords, 0);

    //
    //Validate that data transmitted matches data received, otherwise terminate program.
    //
    uint16_t i;
    for(i = 0; i < myFSIRX0_nWords; i++)
    {
        if(rxDataArray[i] != txBufData[i])
        {
            ESTOP0;
        }
    }
    rxcnt++;
    if(rxcnt >= 35535)
    {

        rxcnt = 0;
        GPIO_togglePin(myBoardLED0_GPIO);
    }


    //
    // Clear the interrupt flag and issue ACK
    //
    FSI_clearRxEvents(FSIRXA_BASE,rxEventSts);
    Interrupt_clearACKGroup(INT_myFSIRX0_1_INTERRUPT_ACK_GROUP);
}
```